First it was put Arduino uno R3 In the simulator then breadboard small then micro servo then Wires have been connected and turned on.

. // C++ code

//

void setup()

{

pinMode(LED\_BUILTIN, OUTPUT);

}

void loop()

{

digitalWrite(LED\_BUILTIN, HIGH);

delay(1000); // Wait for 1000 millisecond(s)

digitalWrite(LED\_BUILTIN, LOW);

delay(1000); // Wait for 1000 millisecond(s)

}